



RECHERCHE











ET INNOVATION



FORMATION

INDUCTIVE VTs: EFFECT OF TEMPERATURE AND VIBRATIONS

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- Context

Measurement setup and testing platform

- Principle
- Generation system
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Test conditions

- Temperature profile
- Vibration parameters
- Harmonic injection

- Results

- Influence of separate factor
- Influence of combined factors
- Conclusions

ITS UNDER REALISTIC CONDITIONS

Assessment of combined influence factor impact on ITs

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CONTEXT

- LITERATURE SHOWS THAT ITS CAN INTRODUCE SIGNIFICANT ERRORS IN PQM
- SPECIFIC NEEDS EXPRESSED BY IEC TC38 "INSTRUMENT TRANSFORMERS" :
 - Define accuracy and uncertainty limits of ITs in PQ measurements
 - Develop suitable reference measuring systems and traceable test procedures
 - Assess the performance with multiple influence factors
- LNE STUDIED TEMPERATURE, VIBRATIONS AND HARMONICS



EURAME

Inductive Voltage Transformers

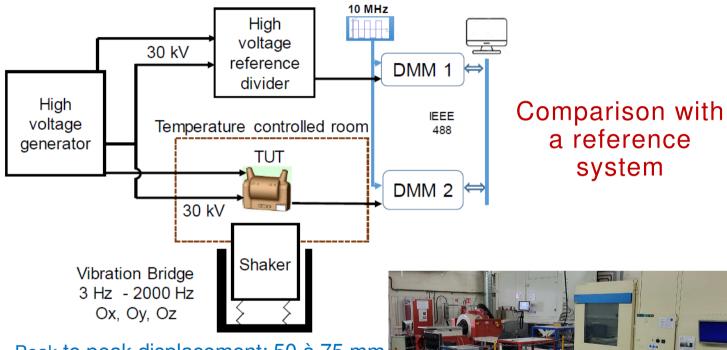
Temperature	Very Low		
Burden	Low		
Positioning	Very low		
Vibration	?		
Self heating	Low		
Frequency linearity up to 9kHz	Very High		
Voltage (current) linearity	Very High		
Long term stability	Very low		
Magnetic field	Medium		
Electric field	Medium		
Influence of overvoltages (overcurrents)	Very High		
Short-circuited secondary	Very high		
Open secondary	Very Low		
Influence of current on voltage	Low		
Influence of voltage on current	Х		

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PRINCIPLE OF MEASUREMENT & TESTING PLATFORM



Peak to peak displacement: 50 à 75 mm

Removable temperature chamber

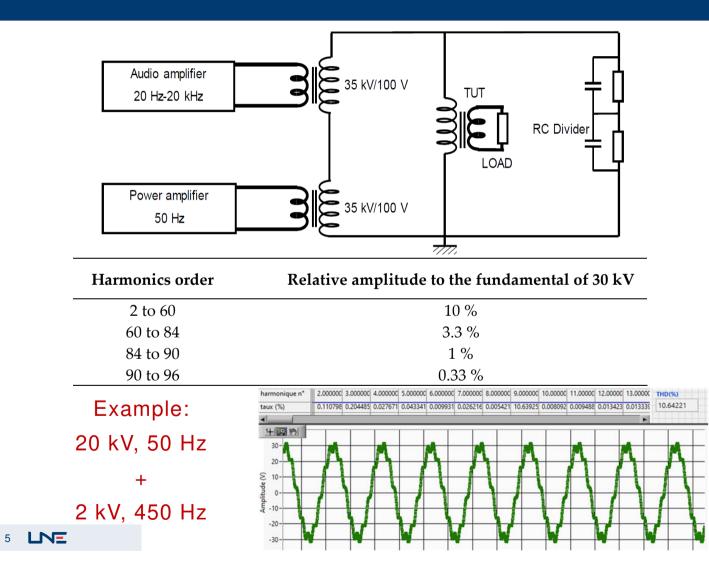
- Temperature : 70°C to 150 °C.
- Speed : 10 °C/min
- Humidity : 10 to 95 %
- Volume : 1,3 m³
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GENERATION SYSTEM





2 step-up transformers 100 V/35 kV class 1 Max $I_s = 10 A$

Power amplifier Bandwidth: 20 kHz Output: 15 A/120 V

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MEASURING SYSTEM



Measurands

Ratio error
$$\varepsilon_n = \frac{k_r V(S_n) - V(P_n)}{V(P_n)}$$

Phase displacement

$$\varphi_n = \varphi(S_n) - \varphi(P_n)$$



where: ε_n - ratio error at the frequency n, $k_r = V p / V s$ - rated TUT scale factor $V(P_n)$ - primary voltage @ frequency n $V(S_n)$ - secondary voltage @ frequency n

LNE voltage divider with uncertainties Ratio error (0,13.*f*+20) ppm Phase displacement (0,13.*f*+20) µrad

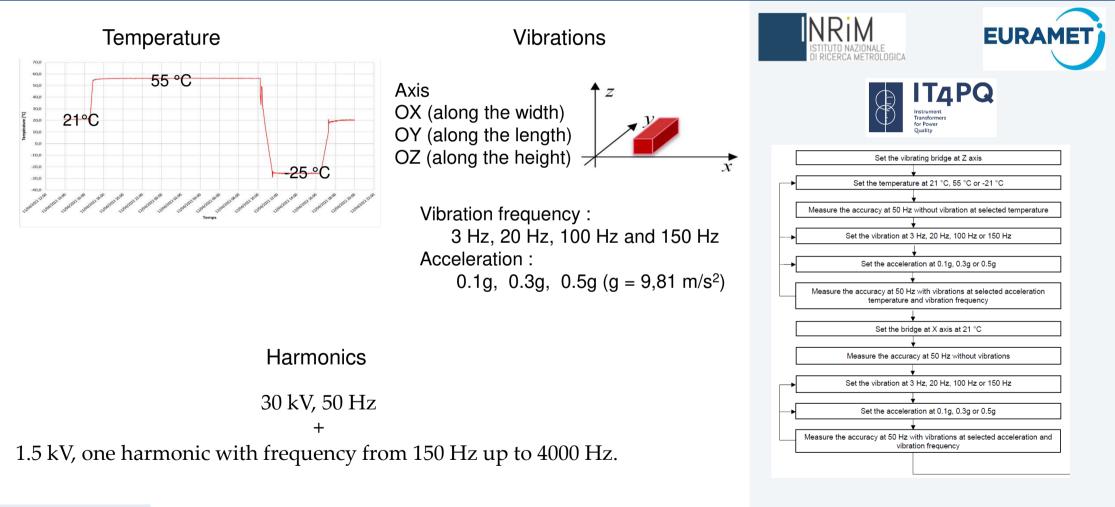
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2 DMM 3458A DC sampling mode Adapted sampling frequency $f_s = \frac{N}{M} f_v$ N - number of samples M - Number of periods

 f_v – frequency of the acquired voltage

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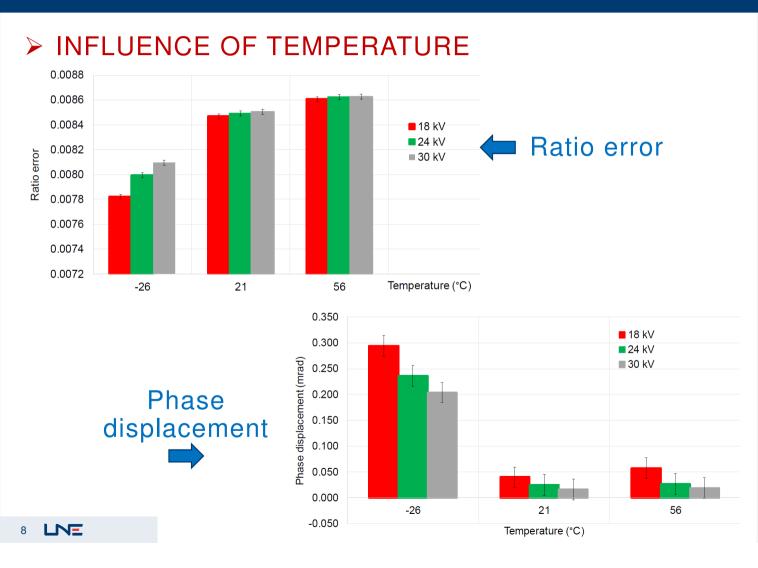
TEST CONDITIONS



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The highest influence is at -25 °C.

Higher influence at low voltage (18 kV)

The differences with respect to 21°C:

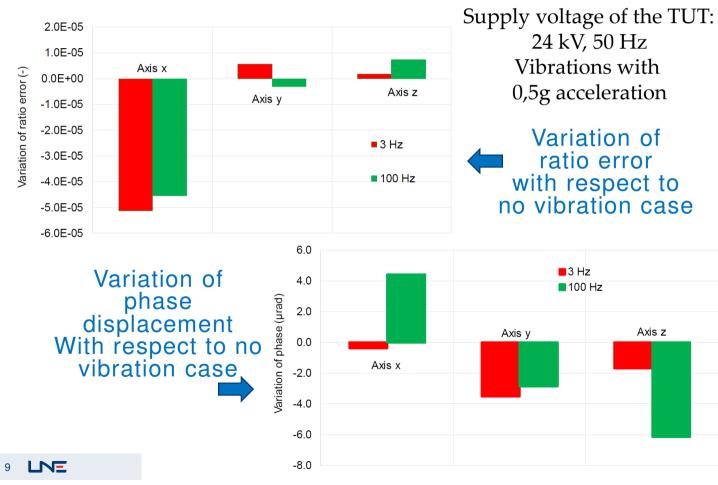
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For ratio error : -6.0·10⁻⁴

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For the phase displacement : 254 µrad

INFLUENCE OF VIBRATIONS





Vibrations with the highest impact :

- along the width of the TUT, axis X
- with frequency of 3 Hz
- with acceleration of $0.5g (4,9 \text{ m/s}^2)$

Variation of ratio error : -5. 10⁻⁵ Variation of phase displacement : few µrad

When changing

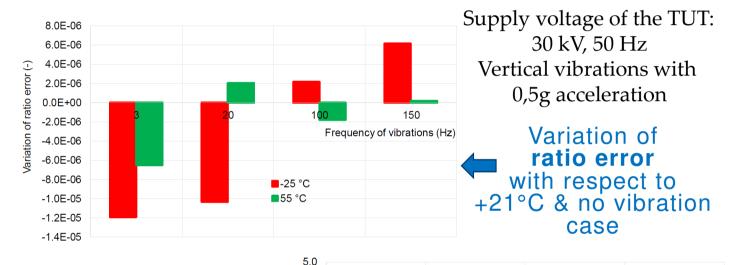
- the orientation,
- the frequency or

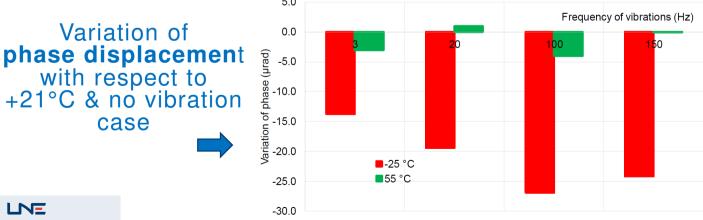
- the acceleration of vibrations, the deviations are less than those produced by the temperature.

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INFLUENCE OF COMBINED TEMPERATURE & VIBRATIONS







Ratio error: the highest deviation from the reference situation is obtained at -25 °C @ 3 Hz vertical vibrations.

Variation of ratio error : -1.5. 10⁻⁵

Phase displacement : more impact at -25 °C @ 100 Hz vertical vibrations Variation of phase displacement : -27 μrad

The two parameters applied simultaneously **did not reveal greater effects** than when they were applied separately.

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> COMBINED TEMPERATURE, VIBRATIONS & HARMONICS

Ratio error and phase displacement @ 50 Hz even if one harmonic exists.

Supply voltage of the TUT: 30 kV, 50 Hz Vertical vibrations, 0.5g (m/s²) with 20 Hz frequency

Reference values @ each temperature : 0 vibrations ; 0 harmonics.

Harmoni	rmoni -25 °C		21°C		+55 °C	
с	Δε	$\Delta oldsymbol{arphi}$	$\Delta \mathbf{\epsilon}$	$\Delta oldsymbol{arphi}$	$\Delta \mathbf{\epsilon}$	$\Delta oldsymbol{arphi}$
(Hz)	(-)	(µrad)	(-)	(µrad)	(-)	(µrad)
150	2.1E-05	2.5	2.2E-05	-10.2	-7.0E-06	-0.9
250	1.8E-05	-3.9	2.7E-05	5.3	6.0E-06	-1.6
350	1.7E-05	-22.0	6.5E-06	11.5	1.0E-05	3.4
450	7.0E-06	-17.2	1.3E-05	17.5	1.3E-05	11.8
550	-1.7E-06	13.8	-3.9E-06	-4.2	1.4E-05	2.2
650	-9.0E-06	-8.1	-1.4E-05	-14.0	2.9E-06	-18.1
1000	-2.0E-05	3.6	3.0E-06	-4.9	2.1E-05	6.4
2000	-2.3E-06	18.0	6.9E-07	-10.1	-9.4E-07	-82
3000	2.4E-05	-8.9	1.8E-05	-11.1	-8.9E-06	-24.4
4000	9.2E-06	15.5	8.6E-08	-6.0	2.8E-05	-5.9



The maximum variation is less than 30 ppm on the ratio error, respectively less than 30 µrad on the phase displacement.

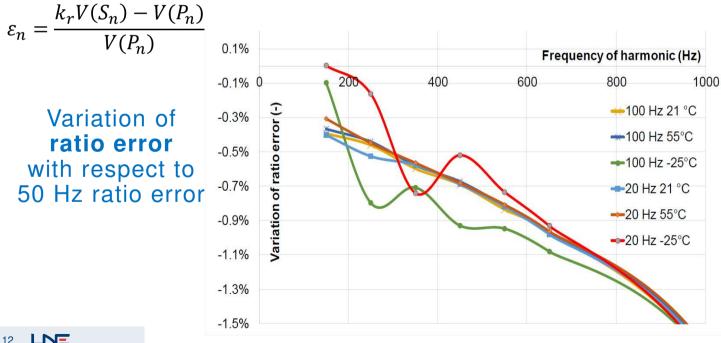
These variations do not go beyond the accuracy class of the transformer.

The TUT operation is not affected by the presence of harmonics and vibrations.

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FREQUENCY RESPONSE OF THE TUT UNDER \succ TEMPERATURE AND VIBRATION

Supply voltage of the TUT: 30 kV, 50 Hz Vertical vibrations, 0.5g (m/s²) with 20 Hz @ 100 Hz frequency Harmonics : 1,5 kV from 150 Hz up to 4 kHz





Using the studied inductive voltage transformer to measure disturbances present on the supply voltages can be done up to 650 Hz and with increased error (deviation up to 1.1% from the 50 Hz precision).

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CONCLUSIONS

The **temperature** is the parameter with the highest influence on the transformer performances.

At 30 kV, -25 °C:

a variation of 400 ppm is obtained for the ratio error and a variation of 200 μ rad is obtained for the phase displacement.

The mechanical vibrations have much less influence, the ratio error varies with 50 ppm the phase displacement varies with tens of µrad.

The presence of the combined factors: temperature, vibrations and onetone harmonic has a very low impact on the inductive VT. Variations in ratio error of less than 30 ppm,

Variations in phase displacement of less than 30 μrad

Inductive voltage transformer measure disturbances present on the supply voltages **with increased error and up to 650 Hz.**



Thank you for your attention.

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